

# Preparing Schrödinger cat states using a neural network

## Presenter:

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## Collaboration:

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## Purpose of this work:

Development and experimental demonstration of a fast neural-network-based method for preparation of families of quantum states

## Main idea:

- consider not a single state but the whole continuous family (here Schrödinger cat states)
- teach neural network to control the system on a selection of states
- use the neural network to quickly generate control for ANY state

First proposal of the idea: F. Sauvage and F. Mintert, PRL 129 (2022)

## Physical system (qubit + cavity)

Jaynes-Cummings Model in the dispersive regime:

$$H(t) = H^{\text{drift}} + H_{\text{qub}}^{\text{ctrl}}(t) + H_{\text{cav}}^{\text{ctrl}}(t) \quad (1)$$

where:

$$H^{\text{drift}} = -\chi n_{\text{phot}} \sigma_z \quad (2)$$

$$H_{\text{qub}}^{\text{ctrl}}(t) = \mu_{\text{qub}} \varepsilon_{\text{qub}}(t) \sigma_+ + \text{h.c.} \quad (3)$$

$$H_{\text{cav}}^{\text{ctrl}}(t) = \mu_{\text{cav}} \varepsilon_{\text{cav}}(t) a^\dagger + \text{h.c.} \quad (4)$$

$$\chi = 238.5 \text{ MHz}, T_1^{\text{qub}} = 35 \text{ us}, T_2^{\text{qub}} = 42 \text{ us}, T_1^{\text{cav}} = 225 \text{ us}$$

## Control task and pulse representation

=> The system is driven during a fixed time-interval

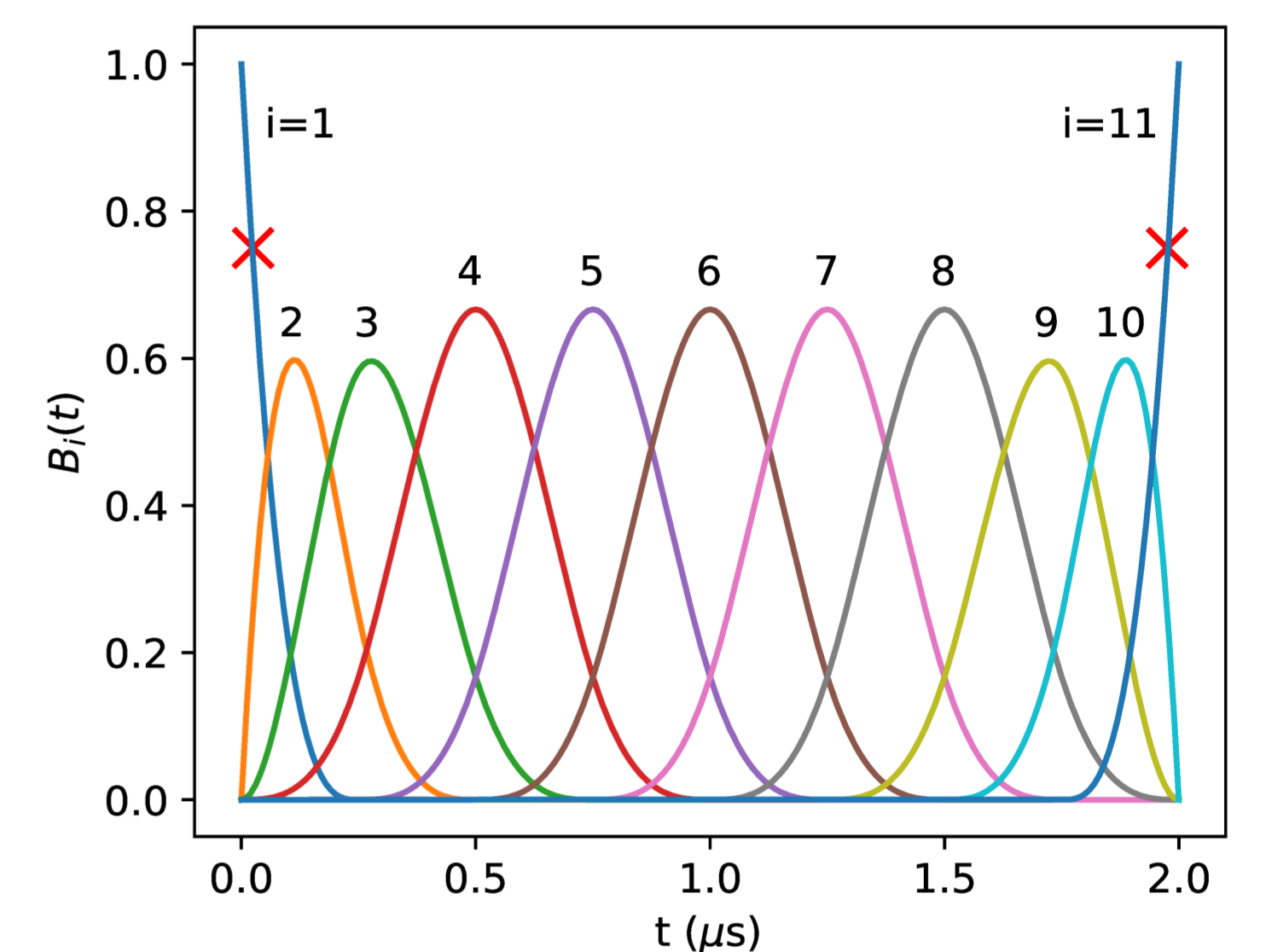
=> We target the family of Schrödinger cat states:

$$|\alpha\rangle + e^{-i\varphi} |-\alpha\rangle \text{ with } \alpha < 4$$

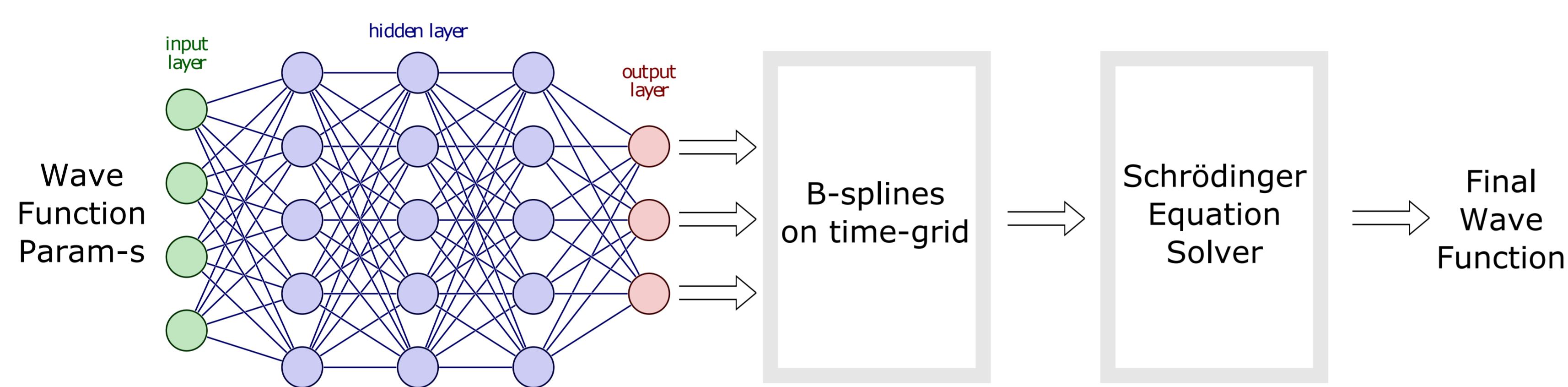
? For all states at once, find the optimal control, that is the 4 fields  $\text{Re } \varepsilon_{\text{qub}}, \text{Im } \varepsilon_{\text{qub}}, \text{Re } \varepsilon_{\text{cav}}, \text{Im } \varepsilon_{\text{cav}}$

We search for the control pulses in the B-spline basis often applied in computational atomic physics

W. R. Johnson, *Atomic Structure Theory: Lectures on Atomic Physics*, Springer, New York (2007)

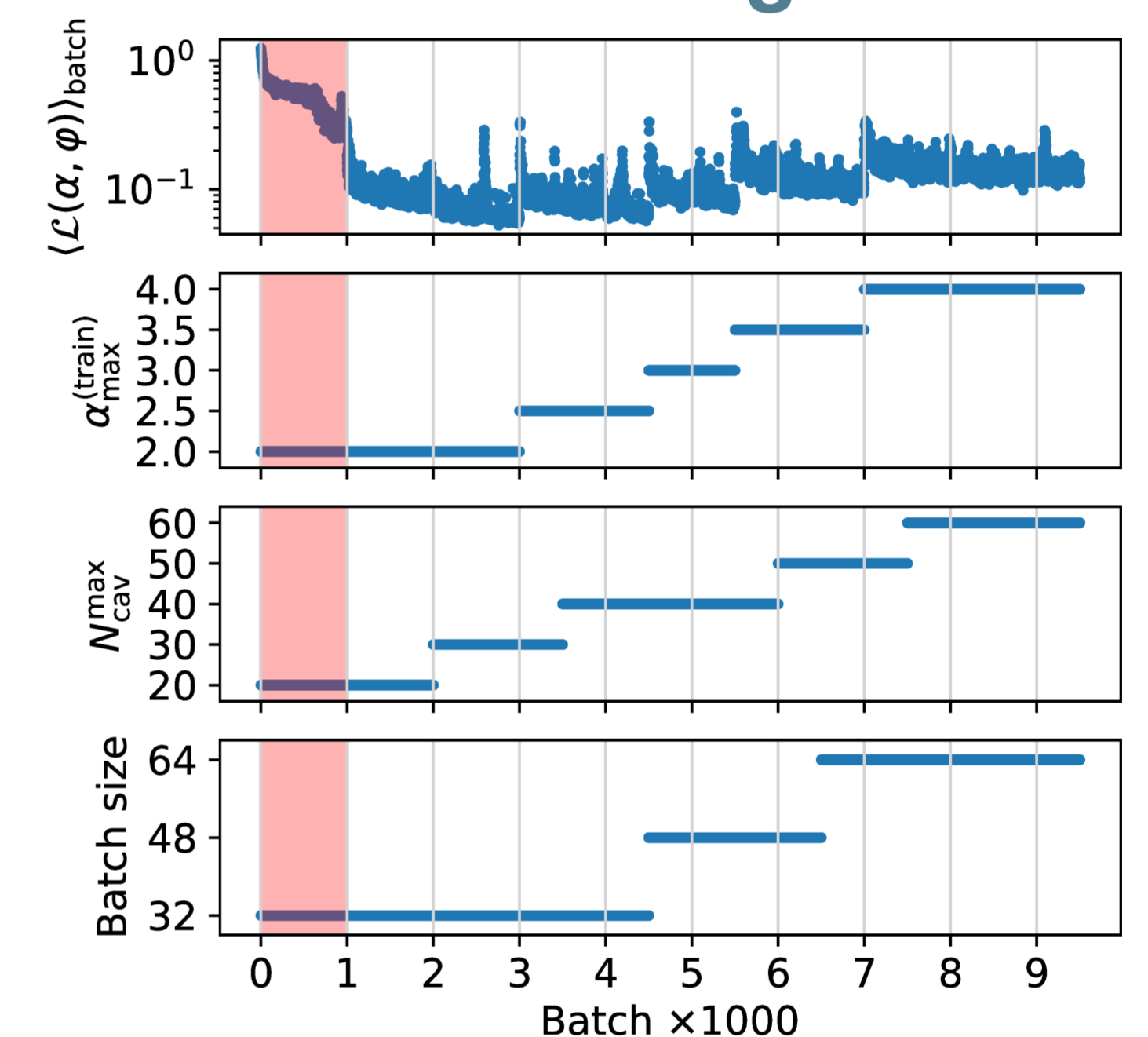


## Data processing pipeline



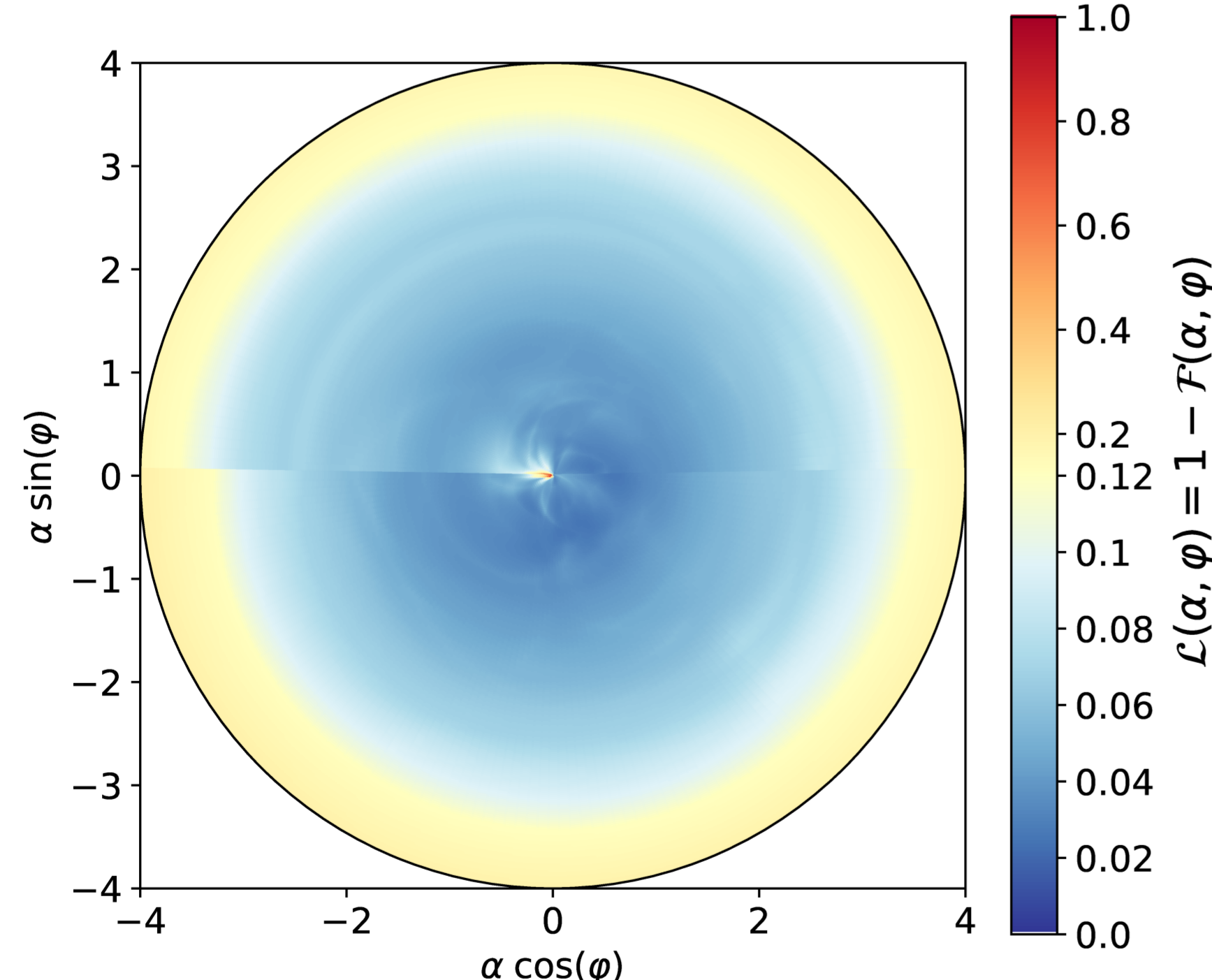
$$\text{Loss}(\alpha, \phi) = \text{Infidelity}(\alpha, \phi) = 1 - \left| \langle \text{target cat} | \text{prepared state} \rangle \right|^2$$

## Training

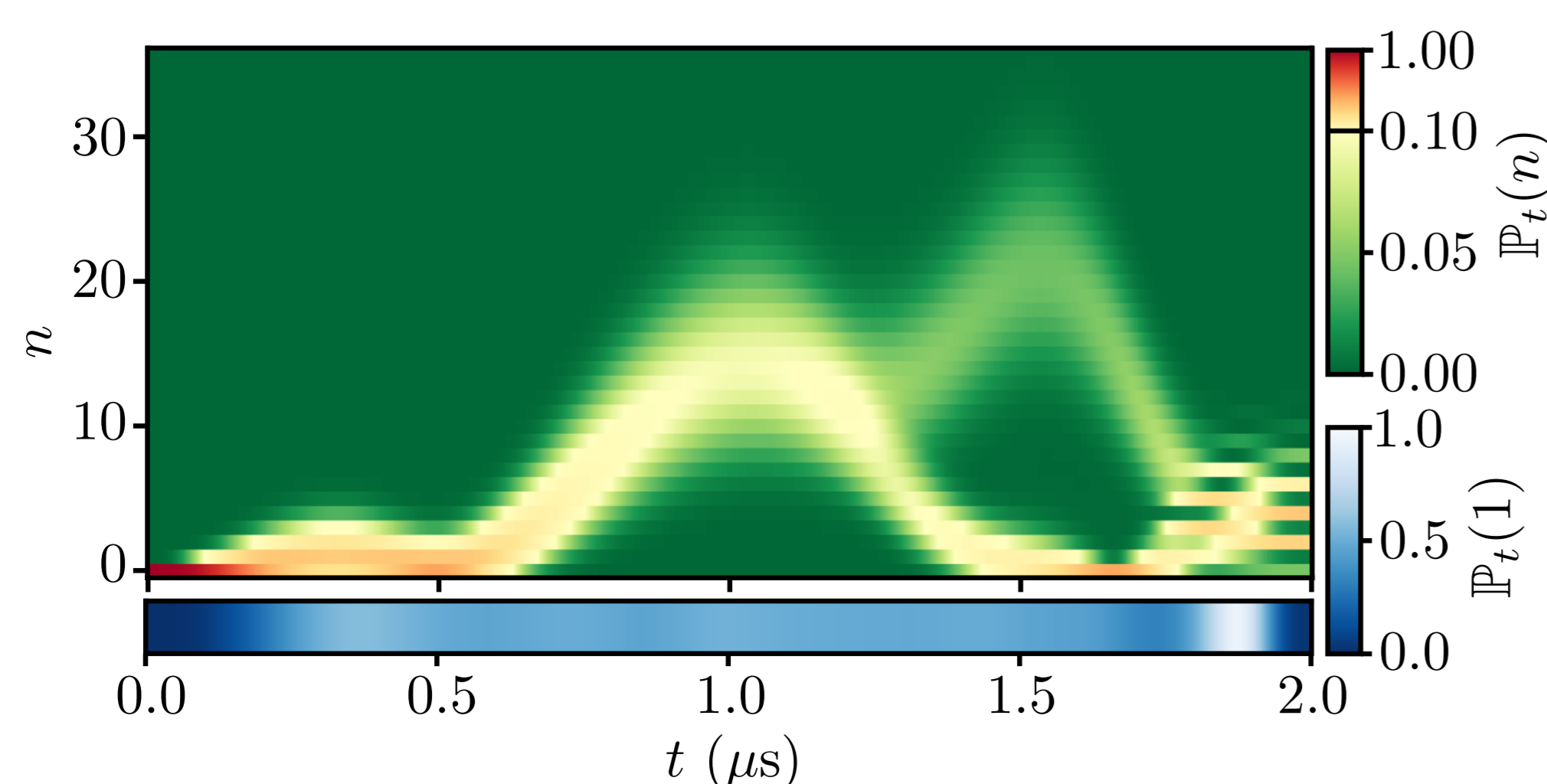


## Theoretical results

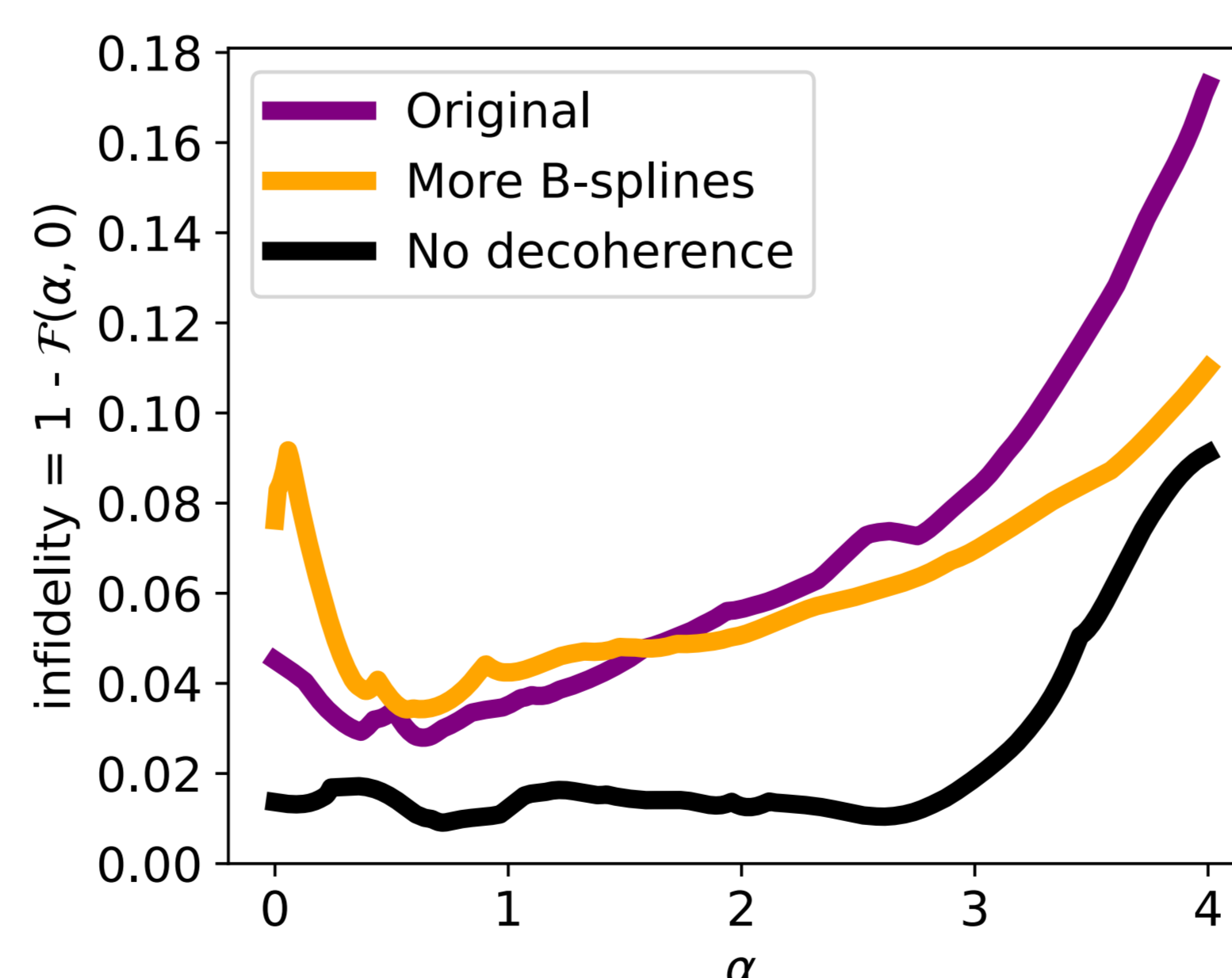
### Obtained infidelities



### Cavity dynamics (α = 2, φ = 0)



### Infidelity sources



- => at small  $\alpha$  due to linear sampling
- => at large  $\alpha$  due to small B-spline set
- => decoherence is the main source

See our manuscript for more details:

H. Hutin, P. Bilous et al.  
arXiv:2409.05557

## Experiment vs theory (α < 2)

